

# Torsional Transcription Theory of the Void

Marco Mariello

# **Torsional Transcription Hypothesis**

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## **Introductory Note**

This paper does not present a proven theory, but rather a formal hypothesis—indeed, a torsional one—concerning the origin of the universe, matter, and spacetime. The choice of the term “transcription” over more technical expressions like “formulation,” “emergence,” or “quantum appearance” stems from an intuition: the emergence of Being from Nothingness was not an explosion, a birth, or an equation—but a passage. A transition resembling a writing, a twisting genesis, the first oscillation of sense, rhythm, or symbol.

We assume here that Void—not as emptiness, but as true absence of being—has undergone a twist, a dynamic instability, or a discontinuity that generated something: a first act of difference, a virtual asymmetry.

From this assumption, the present hypothesis attempts to retrace the path leading from that initial torsional instability to the emergence of the first fields and physical constants. Each step will be speculative but rigorously structured, aiming to offer a conceptual bridge between metaphysical intuition and formal physics.

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## **The Torsional Transcription Theory of the Void**

*(Extended version)*

Marco Mariello

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## **Preliminary Considerations**

The origin of time and matter could derive from a logical-structural crisis generated by a condition of unstable hyper-coherence. An original torsional fluctuation selects coherent configurations through a structural collapse.

This instability could be what generates bifurcations, events, even consciousness.

Let us consider the Dzhanibekov effect, which does not depend on energy dissipation.

It is a purely conservative effect: it occurs even in the absence of friction, with no energy loss, in the vacuum of space. The system conserves energy, angular momentum, and linear momentum, yet remains unstable.

No energy is lost, but dynamic instability amplifies every minimal initial deviation, demonstrating how a conservative system can be unpredictable due to internal geometry, not dissipation.

This makes it an excellent conceptual bridge to the idea of rotation as a universal principle emerging from the void: even there, we might imagine an unstable fluctuation that generates form without dissipating anything.

As if the universe were born from a coherent selection emerging from an unstable and oversaturated condition of incoherent information — a structural transition internal to the domain of non-being.

The grammar of real space is a transcription of the behavior of the void.

The original void can be formalized as the set of all possible information and their contradictions, each with a degree of coherence:

$$\mathbf{N} = \{\mathbf{Ii(c)} \mid \mathbf{c} \in [0,1]\}$$

where  $Ii$  are the possible propositions, and  $c$  represents their degree of coherence.

The torsional collapse selects a coherent subset:

$$\mathbf{R} \subset \mathbf{N}$$

while the residual part:

$$\Delta\psi = \mathbf{N} \setminus \mathbf{R}$$

manifests as physical indeterminacy.

But not only that: the transition is not neutral. Every transcription leaves an ontological scar, an indelible fold that marks the transition from non-being to being. This scar is the geometric memory of the origin: it does not fade, it structures itself. And we find it impressed everywhere — in the limit of measurement, in the breaking of symmetry, in the very form of time.

If the void is not static, but fluctuates with rotational instability, then form, symmetry, even time can emerge as stable transcriptions of an unstable origin.

A bit like a language that stabilizes from babbling — or like standing waves that arise from free interference.

From this perspective:

- Spacetime is not the sheet on which the universe is written, but the grammar produced by the motion of the void.
- Matter is a fold in the syntax: a recurring hesitation of the fluctuation.
- The principle of instability (like the Dzhaniybekov effect) is the first dynamic gesture of creation, the one that breaks perfect indeterminacy.

- The resulting scar is the quantum original sin: the permanent signature of the primordial instability, transcribed into every fundamental physical law.

## Postulate of Torsional Transcription of the Void

The primordial void is not static, but represents an overloaded informational system, unstable both logically and geometrically.

A torsional fluctuation of rotational nature selects, through structural collapse, coherent subsets that are transcribed as space, time, matter, and energy in the observable domain.

The rupture leaves a trace: every emergence is accompanied by an irresolvable discontinuity, a “scar” that marks the memory of the unstable origin.

Formally, the void can be represented as a set:

$$\mathcal{N} = \{I_i(c) \mid c \in [0, 1]\},$$

where  $I_i$  are the possible pieces of information and  $c$  their degree of coherence.

The torsional collapse selects a coherent subset  $\mathcal{R} \subset \mathcal{N}$ , while the residual part  $\Delta\psi = \mathcal{N} \setminus \mathcal{R}$  manifests as physical indeterminacy.

## Corollaries

1. **The torsional fluctuation of the void selects coherent subsets within an unstable informational system.**  
This process produces logical-formal structures that emerge as stable configurations through topological discontinuities or phase transitions.
2. **Space-time emerges as a coherent effect of a periodic symmetry breaking, analogous to the Dzhaniybekov effect, but on an ontological scale.**  
Time is the perceptible effect of a coherent frequency resulting from selective torsional rotation.  
It emerges as a derived coordinate from the persistence of coherent structures within the collapse.
3. **Matter is a localized stasis within the fluctuation — a “word” formed in the turbulent language of origin.**
4. **Energy is not conserved as a primary quantity, but as a secondary effect of the stabilization of an original crisis.**  
Quantum information is the local manifestation of coherent configurations selected in the collapse of the primordial informational system.  
It is not a transported entity, but an emergent property from the residual geometry of transcription.
5. **Every coherent configuration retains within itself an imprint of the original instability:**  
what we call “fundamental physical principles” are stable scars of an unstable fracture.

## Prologue – From Rotation to Torsional Void

### 1. Rotation is Everything

Everything that persists over time, in nature, rotates: from electrons to planets, from fluid vortices to galaxies.

Rotation appears as the minimal form of existence: a state that does not vanish, but repeats itself.  
To be is to spin. Being at rest is pure rotation.

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## *2. The Instability of Rotation*

The observation of the Dzhanibekov Effect reveals that even an object apparently in stable rotation can reorient itself unpredictably.

This instability arises from the geometry of the system and the non-uniform distribution of the moment of inertia.

It is described by Euler's equations for a free rigid body, in which the intermediate axis is unstable:

$I_1, I_2, I_3$  = moments of inertia along the principal axes, with  $I_1 < I_2 < I_3$

The axis with moment  $I_2$  is unstable: even a small perturbation can trigger an inversion.

This suggests that rotation is a "fragile condition" — a tension between stability and fluctuation.

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## *3. The Instability of the Void*

If rotation is the minimal form of being, and if every rotation is unstable...

then even the void itself (understood as non-being) may not be stable.

If the void is overloaded with incoherent information, its instability may generate spontaneous rotations as the geometric manifestation of crisis.

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## *4. Collapse as the Original Event*

Unstable rotation represents a concrete model of internal non-linear dynamics.

Its instability, on a fundamental scale, can be interpreted as a generative principle through coherent selection.

The void, if unstable, generates local torsions: small quantum rotations that, if coordinated, give rise to persistent structures.

And where it breaks, it leaves a scar: no longer absence, but stored tension.

It is from that discontinuity that the Real is born.

# **1. Fundamental Axioms**

## **A1 – Dynamic Void**

The ontological void is not the absence of existence, but the absence of stability — an undetermined field with intrinsic dynamics.

## **A2 – Primary Torsion**

The void fluctuates according to an unstable rotational dynamic, formally describable as free rotation around an intermediate axis of inertia.

### **A3 – Non-dissipation**

This rotation does not involve any loss of information or energy; the crisis is cyclical and conservative.

### **A4 – Transcription**

Emergent structures (time, space, form) are stable or semi-stable transcriptions of the original torsion.

### **A5 – Original Scar**

Every emergent structure retains within itself a geometric-topological imprint of the instability from which it derives.

The Real is not only generated by the Void, but also bears its founding wound: an intrinsic discontinuity that manifests as duality, asymmetry, or limit.

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## **2. Operational Definitions**

- **Torsional Void (TV)**  
An ontological region in which the fluctuation of the void is locally coherent.
  - **Stability Node**  
A temporary configuration in which the fluctuation folds back on itself, generating form/matter.
  - **Symmetry Crisis**  
The internal flip of torsion that breaks the perfect indifference of the void and generates differentiation.
  - **Torsion-Space**  
The topology resulting from millions of simultaneous transcriptions of the torsional void.
  - **Ontological Scar**  
The non-removable structural trace of the original rupture.  
Each coherent node retains a residual tension: what we call indeterminacy, fluctuation, time, or consciousness is the effect of this primal wound that never fully closes.
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## **3. Initial Mathematical Formalization**

(in Word-compatible version)

**Set of informational void:**

$$N = \{I_i(c) \mid i \in I, c \in [0,1]\}$$

**Coherent subset selected by torsional rotation:**

$$R = \{I_i \in N \mid c_i \geq c_{\text{critical}}\}$$

**Non-coherent residue, surviving the transcription:**

$$\Delta\psi = N \setminus R$$

This residue is what survives in the Real as quantum indeterminacy

## Scheme of the Torsional Transcription System of the Void

### Core of the Torsional Void (CTV)

- Imagined as a fluid, transparent sphere with no fixed center.
- Inside it, unstable rotational flows spin around a virtual intermediate axis that continuously changes direction.
- The rotation is conservative but unstable, as in the Dzhanibekov effect.

### Torsional Crisis

- At certain points, dynamic flips occur, generating cyclical breaks in symmetry.
- Each flip is a local originating event: a torsion that closes upon itself, generating a stable node (matter).

### Emergence of Space-Time

- Around the nodes, the fluctuation arranges itself in concentric spiral structures: these are the coordinates of space-time.
- The spirals organize themselves to minimize instability, giving rise to the three spatial dimensions and the frequency of time.

### Matter and Energy

- Stable nodes become particles: oscillating coherences in resonance with the void.
- Energy is intense vibration in the node region; matter is the node itself.
- Some nodes entangle with each other: fields, molecules, complex structures.

### □ □ Formalization of Free Rotation of Rigid Bodies

The dynamics of free rotation (Dzhanibekov model) are described by Euler's equations for a rigid body with no external forces:

For the three principal axes of inertia  $I_1, I_2, I_3$ , with  $I_1 < I_2 < I_3$ :

**Euler's equations (Word-compatible format):**

- $I_1 \cdot d\omega_1/dt = (I_2 - I_3) \cdot \omega_2 \cdot \omega_3$
- $I_2 \cdot d\omega_2/dt = (I_3 - I_1) \cdot \omega_3 \cdot \omega_1$
- $I_3 \cdot d\omega_3/dt = (I_1 - I_2) \cdot \omega_1 \cdot \omega_2$

where  $\omega_1, \omega_2, \omega_3$  are the components of angular velocity along the principal axes.

**The intermediate axis ( $I_2$ ) is unstable:**

small perturbations can cause unpredictable flips in the direction of rotation.

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## □ Types of Torsional Flips

### **Intrinsic Flips (self-induced)**

- Born from the internal torsion of the void itself, without external intervention.
- Generate self-organized symmetry breaks.
- They are the generative core of the system: each intrinsic flip is a wound that closes by creating form.

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### **Extrinsic Flips (induced by external perturbation)**

- Triggered by an interaction between two already stabilized torsions (collision or resonance).
- Introduce relationship and causal interaction between regions of the void.

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## □ □ Operational Overview

**Space** = coherent pattern of torsional fluctuations

**Time** = frequency of stabilization of an oscillation

**Energy** = geometric tension of the field

**Matter** = stationary rotational node

**Causality** = resonance propagated through the field

## **Formalization of the Torsional Geometric Metric**

The torsional field of the void does not generate space as a container, but as an effect of the coherence between rotational fluctuations.

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## **Emergent Geometric Metric**

Let  $\varphi(x,t)$  be a function describing the amplitude of the torsional fluctuation at a point in space-time.

We can define a modified local metric:

$$g_{\mu\nu}(x) = \eta_{\mu\nu} + T_{\mu\nu}(x) \quad g_{\mu\nu}(x) = \eta_{\mu\nu} + T_{\mu\nu}(x)$$

where:

- $\eta_{\mu\nu}$  is the flat Minkowski metric (in local coordinates),
- $T_{\mu\nu}(x)$  represents the geometric contribution of the torsional field.

$T_{\mu\nu}$  can be thought of as a coherent geometric perturbation generated by coherent rotational fluctuations (similar to energy-momentum tensors, but originating from torsional topology, not from matter).



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## Predicted Properties of the Torsional Metric

- Local curvature proportional to torsional stability:  
greater coherence → lower residual curvature → "flat" space;
  - Singularities as phase discontinuities of the torsional field:  
where the node does not close perfectly → topological defects → matter.
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### □ Verification Strategies – Testable Hypothesis

The central hypothesis is that space-time, matter, and forces are geometric emergences from an unstable rotational dynamic in the void.

Since direct access to the primordial void is not possible, we can attempt analogous simulations in accessible contexts:

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## 1. Simulations in Fluids and Condensates (BEC)

- In Bose-Einstein condensates, stable quantized vortices are observed.  
These can simulate self-stabilizing torsional nodes.

### Experimental goals:

- Create rotational instabilities in BECs without dissipation.
  - Verify the emergence of spiral structures or repetitive flips.
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## 2. Nonlinear Optics and Light Solitons

- In nonlinear media, electromagnetic fields can behave like coherent torsions in phase space.

### Possible verifications:

- Creation of rotating solitons (similar to mini-nodes) that remain stable over time.
  - Observation of cyclic instabilities with dynamics similar to the optical Dzhaniybekov effect.
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## 3. Dynamic Casimir Effect – Hints of Quantum Torsion

- The quantum vacuum produces residual forces (Casimir effect).
- If it is torsionally active, asymmetries might be observed in the force between rotating or vibrating structures.

### What to look for:

- Anomalous variations in force value under controlled rotation.
- Phase shifts between standard QED predictions and observations in torsional geometries.

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## 4. Metamaterials and Simulated Curvature

- Certain photonic or acoustic metamaterials mimic curved space geometry.

### Proposal:

- Design a network of materials where the metric is sensitive to coherent fluctuations → test the emergence of curvature from periodic instabilities.
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### □ Observable Indicators

- Stable cyclic flips in the absence of dissipation (BEC, light, fluids)
  - Emergence of frequencies or “local time” from purely spatial systems
  - Topological stabilization resembling particles (rotating solitons)
  - Asymmetric or directional Casimir forces
  - Geometric memories in metamaterials with threshold effect
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## Mathematical Formalization of the Torsional Transcription System of the Void

### 1. Space of the Dynamic Void

The primordial void is conceived as an informational domain of extremely high density, inherently unstable. It is formally defined as the set:

$$N = \{li(c) \mid i \in I, c \in [0,1]\}$$

where:

- $li$  = possible information
- $c$  = degree of coherence
- $I$  = set of informational indices

This space is non-Euclidean, non-differentiable, and lacks predefined dimensions.

### 2. Rotational Instability

Each torsional fluctuation in the void tends to rotate.

Instability naturally emerges due to the internal dynamics of the system.

The rotations can be assimilated to rigid bodies with unequal moments of inertia:

$$I_1 < I_2 < I_3$$

Euler's equations for free rotation (in Word-compatible format):

$$I_1 * (d\omega_1/dt) = (I_2 - I_3) * \omega_2 * \omega_3$$

$$I_2 * (d\omega_2/dt) = (I_3 - I_1) * \omega_3 * \omega_1$$

$$I_3 * (d\omega_3/dt) = (I_1 - I_2) * \omega_1 * \omega_2$$

where:

- $\omega_1, \omega_2, \omega_3$  = components of angular velocity
- $t$  = time

### 3. Torsional Flips and Coherent Selection

Instability leads to periodic flips, similar to those in the Dzhanibekov effect.

These flips function as a selection mechanism:

- Fluctuations that resist the flip stabilize → become coherent nodes
- The others disperse or collapse

This selection generates:

$$R = \{i \in N \mid c_i \geq c_{\text{critical}}\}$$

and the residual:

$$\Delta\psi = N \setminus R$$

### 4. Torsional Wave Function and Active Principle

(complete version with equations)

#### 4.1 – Active Torsional Field

The dynamic void generates an active torsional field, which can be represented through a real or complex function  $\phi(x, t)$ , describing the amplitude and direction of the fluctuation at each point in space-time.

#### 4.2 – Torsional Wave Function

We define the torsional wave function as:

$$\phi(x, t) = A(x, t) \cdot e^{i\theta(x, t)}$$

where:

- $A(x, t)$  is the local amplitude of the torsion
- $\theta(x, t)$  is the rotational phase (internal geometry of the fluctuation)

#### 4.3 – Derivative and Propagation

The time evolution of the torsional field is obtained through:

$$d\phi/dt = \partial A/\partial t \cdot e^{i\theta} + iA \cdot \partial \theta/\partial t \cdot e^{i\theta}$$

This expresses variation in amplitude and variation in phase as separate components of torsional motion.

## 4.4 – Stability Node as Dynamic Nullification

A condition of torsional stability occurs when:

$$d^2\phi/dt^2 \approx 0$$

and simultaneously:

$$\nabla\phi(x) \rightarrow \min$$

The node is therefore a phase-closed fluctuation whose geometry does not vary over time.

## 4.5 – Active Principle and Emerging Causality

The torsional field has an active principle:

it is not only the effect of curvature, but the cause of emerging curvature.

From this arises causality as propagation of coherence:

$$\phi(x_2, t_2) = \phi(x_1, t_1) + \int_1^2 \partial\phi/\partial x \, dx$$

→ the field at a future point is derivable from the coherent field at a previous point.

## 5. Equations of the Torsional Field of the Void

### 5.1 – Torsional Field and Structural Variable

The torsional field represents the system's fundamental active variable.

Each point of space-time is characterized by a fluctuation described as:

$$\phi(x, t)$$

where:

- $x$  is the position in space
- $t$  is time
- $\phi$  is the amount of torsion (orientation or phase)

The field  $\phi$  is a real or complex function representing the dynamic geometry of the void.

### 5.2 – Temporal Derivative and Stationary Node

A stationary node occurs when the torsion stabilizes cyclically over time.

The stability condition is expressed as:

$$d^2\phi/dt^2 \approx 0$$

→ the fluctuation does not accelerate, but maintains a coherent rhythm.

This is the sign that the transcription has produced a node.

## 5.3 – Spatial Gradient and Coherence

The spatial gradient of torsion expresses the variation of the fluctuation in space:

$$\nabla\phi(x, t)$$

Where  $|\nabla\phi|$  is low, coherence is high:

the fluctuation is similar throughout the area  $\rightarrow$  possible node.

Maximum coherence condition:

$$\nabla\phi(x, t) \rightarrow \min$$

## 5.4 – Formal Definition of the Stability Node

A torsional stability node is defined by two simultaneous conditions:

- $\nabla\phi(x, t) \rightarrow \min$
- $d^2\phi/dt^2 \approx 0$

This means that the field fluctuates neither in space nor in time  $\rightarrow$

it has reached a compact, closed, persistent form.

## 5.5 – Torsional Frequency and Local Time

The frequency with which a coherent torsion repeats at a point defines local time:

$$T(x) = 1 / f(x)$$

Where  $f(x)$  is the frequency of torsional coherence.

Time is not absolute:

it is the internal cyclicity of a coherent node in the torsional field.

## 6. Emergentist Geometric Metric

### 6.1 – Space as an Effect of Coherence

Space is not a preexisting structure, but emerges from the coherence of the torsional field.

Where fluctuations are stable and distributed, a local metric configuration is generated that we can call 'space'.

### 6.2 – Metric as Local Transcription of Torsion

The metric  $g_{\mu\nu}(x)$  at a point  $x$  in space-time is the geometric trace of residual torsion.

It can be written as:

$$g_{\mu\nu}(x) = \eta_{\mu\nu} + T_{\mu\nu}(x)$$

where:

- $\eta_{\mu\nu}$  is the flat Minkowski metric (classical empty space)
- $T_{\mu\nu}(x)$  is the scar tensor: it expresses the curvature generated by torsion

### 6.3 – Torsional Field as the Origin of Geometry

The geometry of space-time is not caused by matter, but by the geometric persistence of torsion in the primordial void.

Matter and gravitational field are not primary concepts, but forms of torsional coherence.

### 6.4 – Geometric Definition of Coherence

Local coherence  $C(x)$  can be linked to the gradient of torsion:

$$C(x) \propto 1 / |\nabla\phi(x)|$$

where:

- $|\nabla\phi(x)|$  measures the spatial variation of torsion
- the metric is more regular where torsion varies less

Where  $C(x)$  is high, space is flat

Where  $C(x)$  is low, emergent curvature appears

### 6.5 – Folded Geometries as a Scar Effect

Every curvature of space-time can be reinterpreted as the topological trace of an original torsional node.

The emerging metric is not continuous everywhere:

it presents residual tensions, just like the inner folds in a stretched fabric.

### 6.6 – Singularities as Failures of Coherence

A singularity is not an infinite quantity, but a point where coherence fails:

torsion cannot stabilize, and the metric collapses.

The structure  $g_{\mu\nu}(x)$  becomes undefined where the field  $\phi(x, t)$  loses continuity or vanishes.

Singularities are logical holes in the language of reality:

**not errors, but extreme signs of the original scar.**

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## 7. Time, Frequency, and Node

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### 7.1 – Time is not an external coordinate

In the system of torsional transcription, time is not an absolute axis upon which events are projected.

It is instead a local dynamic effect, born from the frequency with which a fluctuation stabilizes.

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## 7.2 – Time as rhythm of coherence

Each region of the torsional field has a stabilization frequency:  
an internal rhythm that marks its persistence.

It is defined as:

$$T(\mathbf{x}) = 1 / f(\mathbf{x})$$

where:

- $T(\mathbf{x})$  = perceived local time
  - $f(\mathbf{x})$  = frequency of torsional coherence at that point
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## 7.3 – Node as local source of time

A stability node is not only a spatial form, but also an internal cadence.  
Each node has its own coherent rhythm, which manifests as local time.  
The presence of a node stabilizes the surrounding field, generating a dominant frequency.

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## 7.4 – Variation of time between regions

Since  $f(\mathbf{x})$  varies from point to point, so does  $T(\mathbf{x})$ .  
It follows that time does not flow uniformly everywhere:  
it is a function of the local torsional geometry.

In regions of high coherence:

- $f(\mathbf{x})$  is constant
- $T(\mathbf{x})$  is defined, linear

In unstable zones or at the edge of a node:

- $f(\mathbf{x})$  varies
  - $T(\mathbf{x})$  is distorted
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## 7.5 – Emergence of causality

Causality is not imposed from the outside, but derives from the possibility of propagating torsional coherence between nodes.

If  $\phi(\mathbf{x}_1, t_1)$  is coherent with  $\phi(\mathbf{x}_2, t_2)$ , and the two regions are connected by a continuous torsional flow, then one can write:

$$\phi(\mathbf{x}_2, t_2) = \phi(\mathbf{x}_1, t_1) + \int_1^2 \partial\phi/\partial\mathbf{x} \, d\mathbf{x}$$

the subsequent configuration derives from the previous one →

This defines an emergent causality, not deterministic, but topological.

# 8. Minimal Theory of the Torsional Field of the Void

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## 8.1 – Fundamental Postulate (P0)

The Void is not empty, but unstable.  
Instability generates local torsional fluctuations which, if coherent, give rise to:

- space •
- time •
- energy •
- matter •

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## 8.2 – Objects of the Theory

Object	Symbol	Meaning
Torsional Field	$\vec{\beta}(x, t)$	Rotational fluctuation of the Void
Torsional Curvature	$\mathcal{K} = \nabla \times \vec{\beta}$	Local instability
Emerging Metric	$g_{\mu\nu} = \langle \vec{\beta}^\mu, \vec{\beta}^\nu \rangle$	Geometry of space
Local Time	$\tau = 1 / \omega$	Frequency of coherence
Node	$\nabla \times \vec{\beta} = \lambda \vec{\beta}$	Matter as torsional soliton

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## 8.3 – Fundamental Equations

**(E1) Field evolution**  
$$\partial \vec{\beta} / \partial t = \vec{\beta} \times (\nabla \times \vec{\beta}) - \gamma \nabla (\nabla \cdot \vec{\beta})$$
  
Describes the evolutionary dynamics of the torsional field.  
It is a variant of the Navier-Stokes equation without dissipation, adapted to the geometric context.

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**(E2) Metric definition**  
$$g_{\mu\nu} = \langle \vec{\beta}^\mu, \vec{\beta}^\nu \rangle$$
  
The metric of space emerges as the inner product between local components of the field.

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**(E3) Stationary node (matter)**  
$$\nabla \times \vec{\beta} = \lambda \vec{\beta}$$



A stable torsional node (matter) is a rotation eigenvalue.  
The constant  $\lambda$  represents its geometric intensity.

#### (E4) Field energy

$$E = \int [\alpha |\vec{\beta}|^2 + \beta |\nabla \times \vec{\beta}|^2] d^3x$$

Total energy of the system as the sum of torsional intensity and curvature.

The coefficients  $\alpha$  and  $\beta$  regulate the balance between stability and instability.

#### (E5) Local time

$$\tau = 1 / \omega(\mathbf{x})$$

where  $\omega(\mathbf{x})$  is the local torsional frequency.

Time is not absolute, but derives from the cyclicity of torsional coherence.

Concept	Torsional Interpretation
Original Void	Informational saturation in an unstable state
Torsion	Spontaneous rotational fluctuation in the Void
Flip	Cyclical breaking of symmetry
Node	Local stabilization of torsion $\rightarrow$ matter
Coherence	Spatial and temporal continuity of the torsional field
Residual $\Delta\psi$	Non-transcribable information $\rightarrow$ physical indeterminacy
Time	Local frequency of node stabilization
Space	Geometry emerging from the coherent distribution of torsion
Energy	Intensity of torsional fluctuation + residual curvature
Causality	Propagation of coherence between nodes $\rightarrow$ topological, non-deterministic effect
Metric $g_{\mu\nu}(\mathbf{x})$	Deformation of flat metric by the torsional tensor $T_{\mu\nu}(\mathbf{x})$
Indeterminacy	Persistence of $\Delta\psi$ after collapse of coherence
Scar	Structural trace of the original collapse, visible in all physical laws
Torsional field $\vec{\beta}(\mathbf{x}, t)$	Primary variable of the system
Evolution equation (E1)	$\partial \vec{\beta} / \partial t = \vec{\beta} \times (\nabla \times \vec{\beta}) - \gamma \nabla (\nabla \cdot \vec{\beta})$
Stationary node (E3)	$\nabla \times \vec{\beta} = \lambda \vec{\beta}$
Field energy (E4)	$E = \int [\alpha$
Local time (E5)	$\tau = 1 / \omega(\mathbf{x})$

# Appendix 1 – Wave and Particle as Torsional Geometry

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## 1. Conceptual Premise

In the unstable void, torsion is not a disturbance:  
it is the first form of existence.

It can manifest in two ways:

- Node** (localization): fluctuation that closes → particle
  - Wave** (propagation): fluctuation that vibrates → possibility
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## 2. Simplified Mathematical Connection

The same torsional fluctuation  $\beta^{\rightarrow}(\mathbf{x}, t)$  can assume two forms:

**Node (localized):**

$$\beta^{\rightarrow}(\mathbf{x}, t) = \beta^{\rightarrow}_0 \cdot e^{i\omega t} \cdot f(\mathbf{x})$$

**Wave (distributed):**

$$\beta^{\rightarrow}(\mathbf{x}, t) = \beta^{\rightarrow}_0 \cdot e^{i(\mathbf{k} \cdot \mathbf{x} - \omega t)}$$

Both are different manifestations of the same torsional field,  
as in quantum mechanics.

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## 3. Symbolic Summary of the Transformation

State	Torsion	Manifestation
Pre-collapse (wave)	Open	Vibration of possibility
Observation	Break	Forced closure
Post-collapse	Node	Real particle

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## 4. Torsional Formulation of Indeterminacy

Let  $\beta^{\rightarrow}(\mathbf{x}, t)$  be a torsional function of the Void.

Then:

- Position** is related to the localization of the node
- Momentum** is related to the rotational frequency

The minimal product is fixed by a torsional constant:

$$\Delta_{\tau\mathbf{x}} \cdot \Delta_{\tau\mathbf{p}} \geq \kappa$$

where  $\kappa$  is the minimal curvature product compatible with the stability of a node.

In a natural extension:  
 $\kappa \equiv \hbar/2$ ,  
but the theory allows for generalizations.

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5. Link Between Original Torsion and Quantum Effects

Original Torsion (pre-real)	Effect in the Real
Inability to close perfectly	Indeterminacy
Differentiation without cause	Wave-particle duality
Unstable persistence	Quantum coherence
Intrinsic non-locality	Entanglement

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6. Operational Definition of Torsional Consciousness

We define **torsional consciousness** as a fluctuation  $\beta_{-c}^{\rightarrow}$  such that:

$$\beta_{-c}^{\rightarrow}(x, t) = F[\beta_{-c}^{\rightarrow}(x, t)]$$

where  $F$  is a dynamic self-observation operator.  
The fluctuation contains an image of itself,  
updated over time.

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7. Conscious Density

The **conscious density**  $\rho_{-c}(x, t)$  is defined as:

$$\rho_{-c}(x, t) = \int \beta_{-c}^{\rightarrow}(x, t - \tau) \bullet \beta_{-c}^{\rightarrow}(x, t) \, d\tau$$

Consciousness grows with the ability of the node  
to resonate with its own history.

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# Appendix 2 – Conservation of the Primordial Syntax

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## 1. Origin: the Instability of the Void

The original Void is not absence, but an unstable totality.  
The torsional fluctuations that emerge within it are organized according to an internal syntax, a rotational logic that cannot be perfectly closed.

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## 2. Original Syntax

Primordial torsion is not random:  
it follows structural rules that determine:  
how it can curve •  
how it can stabilize •  
how it can reflect itself •

These rules constitute the syntax of the Void:  
a grammar of dynamic self-resonance.

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## 3. Transcription into the Real

The torsional collapse does not erase the syntax, but translates it into manifest form.  
The concepts of energy, space, time, duality, and consciousness are transcribed effects of the original tensions.

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## 4. Principle of Syntactic Conservation

Every physical law can be read as a coherent translation of an original torsional rule.  
The Real does not invent — it transcribes the grammar of the Void.  
It preserves its symmetries, but also its ruptures.

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## 5. Correspondence Table

Original Instability	Transcribed Effect in the Real
Rotational non-closure	Uncertainty principle
Persistence of fluctuation	Quantization of energy
Internal asymmetry	Irreversible time
Tension between states	Wave-particle duality

## **Original Instability**

Topological self-reflexivity

## **Transcribed Effect in the Real**

Consciousness (reflex effect)

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## **6. Conclusion**

The Real is nothing but torsion reflecting upon itself and organizing.  
It is not an order imposed from the outside,  
but an unstable equilibrium stored in the shape of things.

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## Appendix 3 – The Scar (Quantum Original Sin)

### □ Premise

The original Void is not absence, but total informational saturation.

It contains every possible proposition, its negation, every contradiction, every coherence.

Formally:

$$\mathbf{N} = \{\mathbf{Ii(c)} \mid \mathbf{i} \in \mathbf{I}, \mathbf{c} \in [0,1]\}$$

where:

- $\mathbf{Ii}$  = logical-informational proposition
- $\mathbf{c}$  = degree of coherence (from 0 to 1)
- $\mathbf{I}$  = set of informational indices

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### ⚡ The Structural Collapse

The torsional crisis selects a coherent subset, which is transcribed into the Real:

$$\mathbf{R} = \{\mathbf{Ii} \in \mathbf{N} \mid \mathbf{ci} \geq \mathbf{c\_critical}\}$$

Everything that does not reach the critical threshold is excluded from coherent transcription:

$$\Delta\psi = \mathbf{N} \setminus \mathbf{R}$$

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### □□ The Residue that Survives

This residual  $\Delta\psi$  cannot be expelled:

it remains structurally active, as intrinsic indeterminacy.

It is the "scar" left by the collapse:

a geometric tension that persists as a structure impossible to eliminate.

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### □ Observable Effects of the Residue

Heisenberg's uncertainty is the observable effect of •  $\Delta\psi$  within the transcribed domain.

Wave/particle duality derives from the coexistence of •  $\mathbf{R}$  (current coherence) and  $\Delta\psi$  (incoherent interference).

Quantum non-locality is the dynamic manifestation of the unresolved tension between these two domains. •

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### □ Action of the Observer

The observer does not create reality:

they force it locally, demanding coherence.

This imposition causes the temporary collapse of the fluctuation into a localized node.

But the residue  $\Delta\psi$  does not disappear: it returns in the next cycle, as persistent noise.

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## □ Formal Rewriting in Physical Terms

### 1. Nature of the informational vacuum:

$$\mathbf{N} = \{\mathbf{Ii(c)} \mid \mathbf{i} \in \mathbf{I}, \mathbf{c} \in [0,1]\}$$

### 2. Coherent transcription (collapse):

$$\mathbf{R} = \{\mathbf{Ii} \in \mathbf{N} \mid \mathbf{ci} \geq \mathbf{c\_critical}\}$$

### 3. Residue:

$$\Delta\psi = \mathbf{N} \setminus \mathbf{R}$$

### 4. Structural rupture:

The original fracture leaves a curvature in the induced metric:

$$\mathbf{g_{\mu\nu}(x)} = \mathbf{\eta_{\mu\nu}} + \mathbf{T_{\mu\nu}(x)}$$

where:

- $\mathbf{T_{\mu\nu}(x)}$  is the contribution of the scar

It does not derive from matter, but from non-transcribed incoherent information •

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## □ Conclusion

The Scar is the permanent signature of the transition from the Void to the Real.

It is not an accidental trace, but a constitutive structure.

Where we measure indeterminacy, there is •  $\Delta\psi$

Where we perceive the irreducibility of duality, there is the Scar •

Where time has direction, there is a residual curvature remembering the original instability •

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